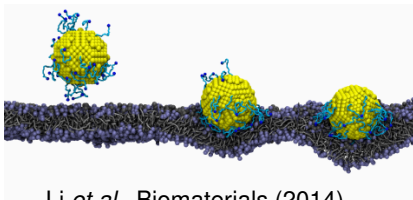


Brownian motion near cell membranes

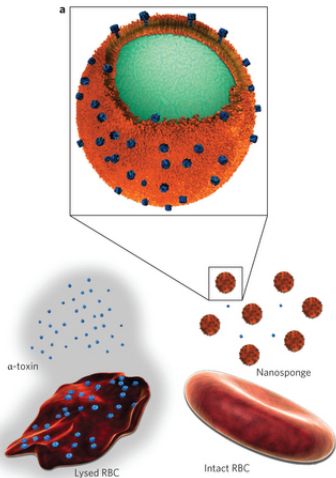
Abdallah Daddi-Moussa-Ider, Achim Guckenbergler and Stephan Gekle

University of Bayreuth
Biofluid Simulation and Modeling

Flowing Matter 2016
Porto, January 12, 2016



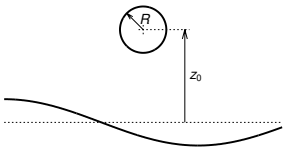
Li *et al.*, Biomaterials (2014)



Hu *et al.*, Nat Nano (2013)

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Particle mobility

$$V_{\alpha}(\omega) = \mu_{\alpha\beta}(\mathbf{r}_0, \omega) F_{\beta}(\omega)$$

$$\mu_{\alpha\alpha}(\omega) = \mu_0 \exp\left(-R\sqrt{\frac{-i\rho\omega}{\eta}}\right) + \Delta\mu_{\alpha\alpha}(\omega)$$

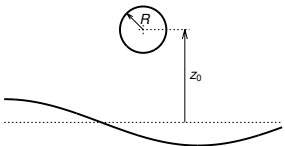
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$$-\rho \frac{\partial \mathbf{v}}{\partial t} + \eta \nabla^2 \mathbf{v} - \nabla p + \mathbf{F} \delta(\mathbf{r} - \mathbf{r}_0) = 0$$

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The particle mobility serves as an input for diffusion.

How does the membrane affect the particle diffusional dynamics?



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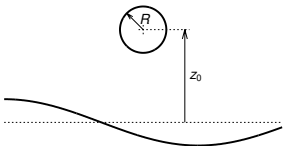
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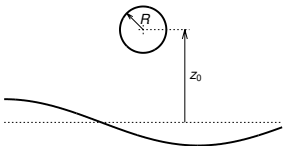
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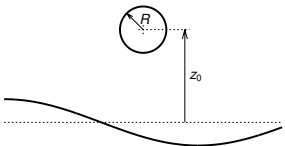
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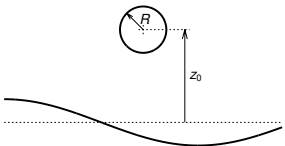
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Traction jumps

$$\text{Skalak } \Delta f^\beta = -\frac{\kappa_S}{3} (\Delta_{\parallel} u_\beta + (1 + 2C)\mathbf{e}_{,\beta}), \quad \beta \in \{x, y\}$$

$$\text{Helfrich } \Delta f^z = \kappa_B \Delta_{\parallel}^2 u_z$$

with $C = \kappa_A/\kappa_S$, $\Delta_{\parallel} = \partial_{,xx} + \partial_{,yy}$ and $\mathbf{e} = u_{x,x} + u_{y,y}$ is the dilatation.

Velocity continuity

$$\mathbf{v}|_{z=0^+} - \mathbf{v}|_{z=0^-} = 0$$

No-slip condition

$$\mathbf{v} = \left. \frac{d\mathbf{u}}{dt} \right|_{z=0}$$

Resolution procedure

- Temporal Fourier transform $t \rightarrow \omega$
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The fluid velocity field can then be found in Fourier space.

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Mobility corrections

- Apply back spatial Fourier transform.
- Identify the velocity Green's functions from $\mathbf{v}_\alpha = \mathcal{G}_{\alpha\beta} \mathbf{F}_\beta$.
- Find the mobility correction in the point particle approximation.

$$\Delta\mu_{\alpha\beta}(\mathbf{r}_0, \omega) = \lim_{\mathbf{r} \rightarrow \mathbf{r}_0} \left(\mathcal{G}_{\alpha\beta}(\mathbf{r}, \mathbf{r}_0) - \mathcal{G}_{\alpha\beta}^{(0)}(\mathbf{r} - \mathbf{r}_0) \right)$$

where $\mathcal{G}_{\alpha\beta}^{(0)}$ is the infinite space Green's function.

- The mobility correction tensor is diagonal such that $\Delta\mu_{xx} = \Delta\mu_{yy} = \Delta\mu_{\parallel}$ and $\Delta\mu_{zz} = \Delta\mu_{\perp}$.
- $\Delta\mu_{\parallel}$ and $\Delta\mu_{\perp}$ are conveniently expressed in terms of the following dimensionless numbers

$$\beta = \frac{12z_0\eta\omega}{\kappa_S + \kappa_A}, \quad \beta_B = 2z_0 \left(\frac{4\eta\omega}{\kappa_B} \right)^{1/3}, \quad \sigma = z_0 \left(\frac{\rho\omega}{\eta} \right)^{1/2}$$

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Brownian dynamics

The particle dynamics is governed by the generalized Langevin equation

$$m \frac{dv_\alpha}{dt} = - \int_{-\infty}^t \zeta_\alpha(t-t') v_\alpha(t') dt' + F(t), \quad \alpha \in \{\parallel, \perp\}$$

The particle mean squared displacement (MSD) is computed as

$$\langle x_\alpha(t)^2 \rangle = 2 \int_0^t (t-s) \phi_{v,\alpha}(s) ds$$

Kubo, Toda and Hashitsume, Stat. Phys. II (1985)

$$\text{Excess MSD: } \Delta_\alpha(t) := 1 - \frac{\langle x_\alpha(t)^2 \rangle}{2D_0 t} = 1 - \frac{D(t)}{D_0}, \quad D_0 = k_B T \mu_0$$

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A completed double layer boundary integral equation method is used.

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The traction jumps are computed according to the Skalak and Helfrich models.

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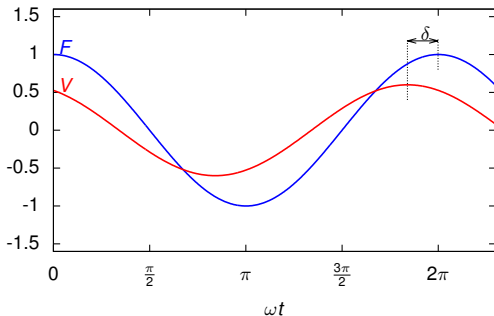
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Mobility simulations

- An oscillating **force** $F_0 e^{i\omega t}$ is applied on the particle.
- The recorded **velocity** is fitted as $V_0 e^{i(\omega t + \delta)}$.
- The frequency dependent mobility is evaluated from

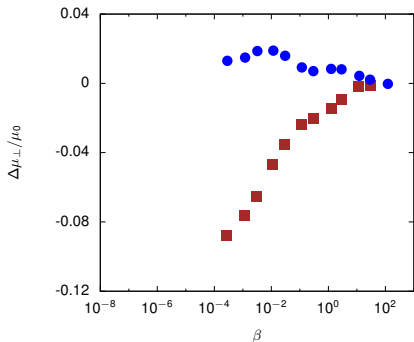
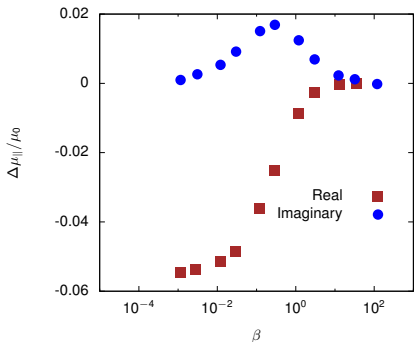
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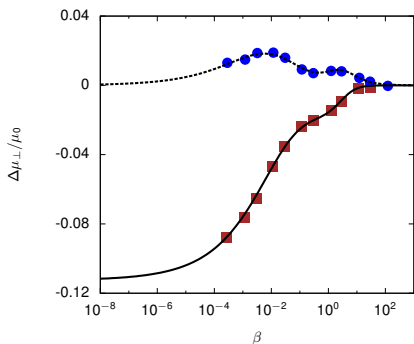
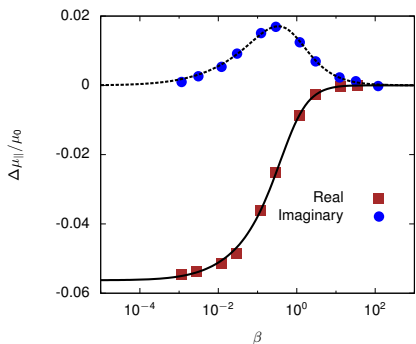
Analytics v.s. numerics

A series of simulations are performed over a range of frequencies. Here $R/z_0 = 0.1$ and $\kappa_B/R^2\kappa_S = 0.5$.



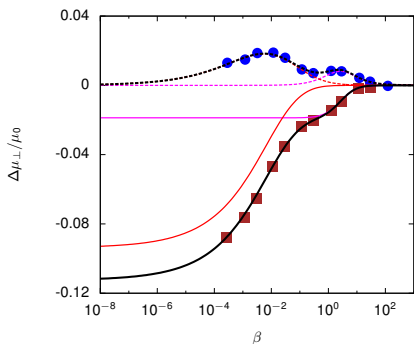
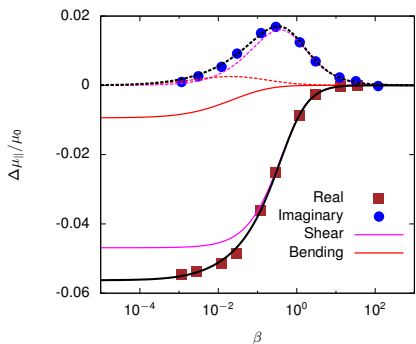
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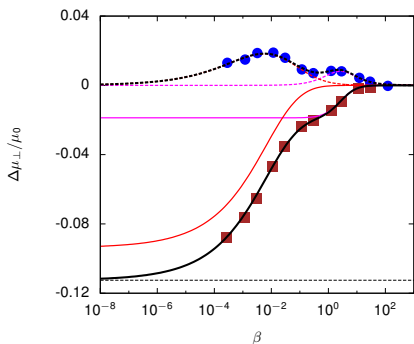
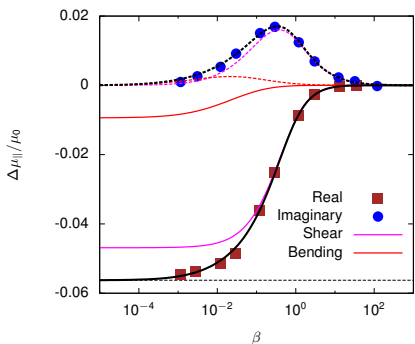
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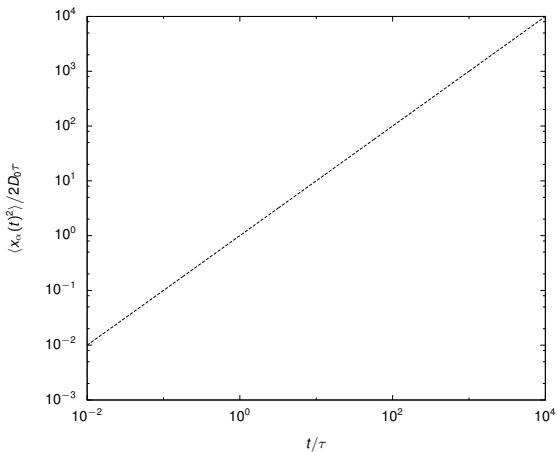


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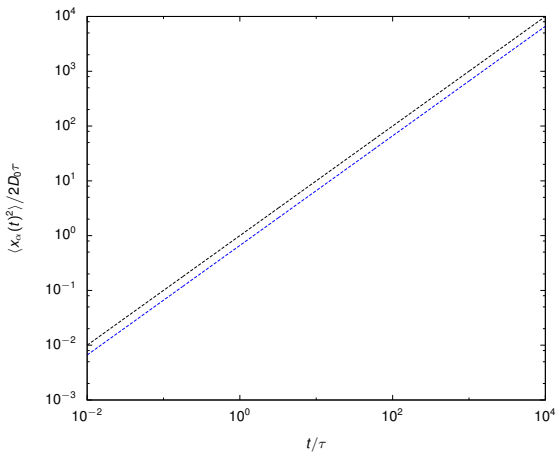


MSD



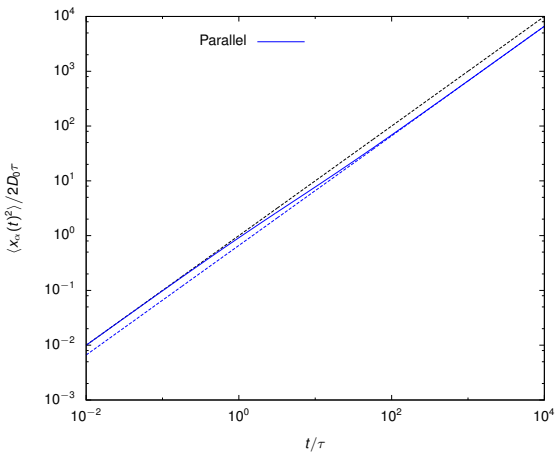
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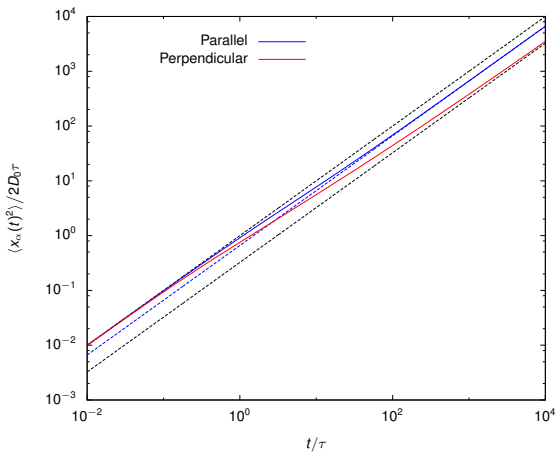
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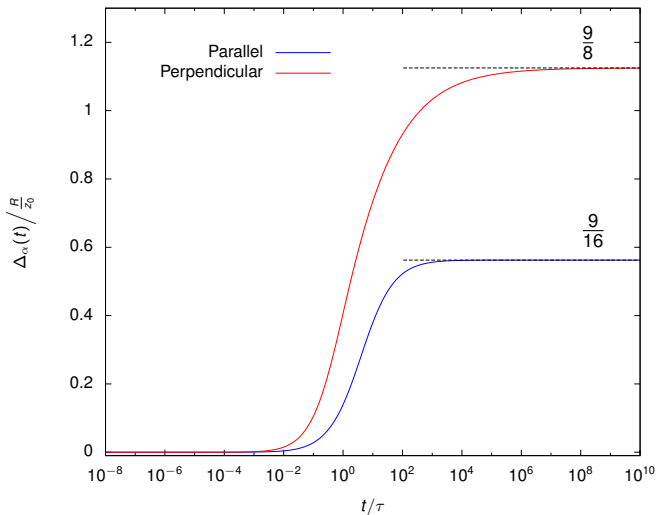
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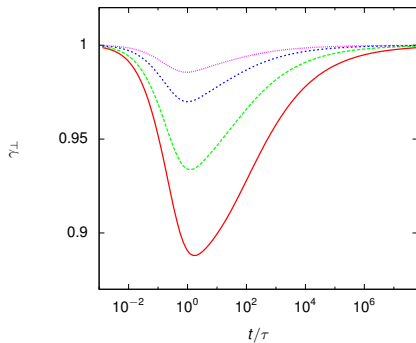
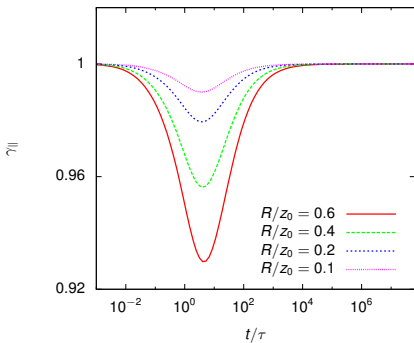
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Excess MSD



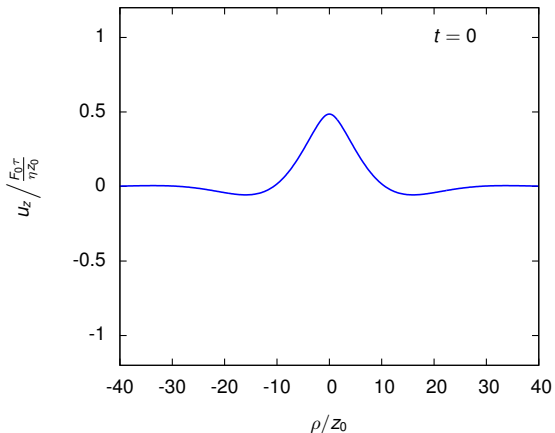
Scaling exponent

$$\gamma_\alpha(t) := \frac{d \ln \langle x_\alpha(t)^2 \rangle}{d \ln t} = 1 - \frac{t \Delta'(t)}{1 - \Delta(t)}$$



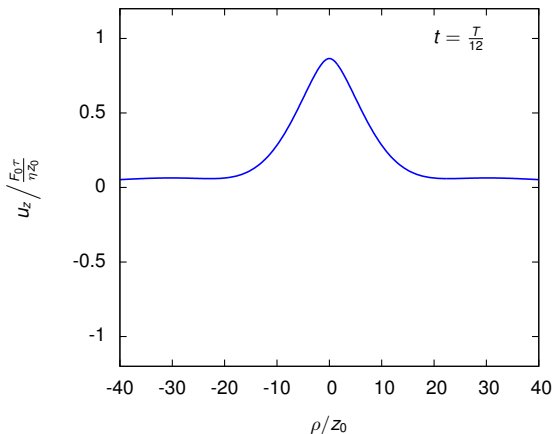
Membrane vertical displacement (Perpendicular motion)

- The motion of the interface can be investigated.
- Here the force is applied perpendicular to the membrane.



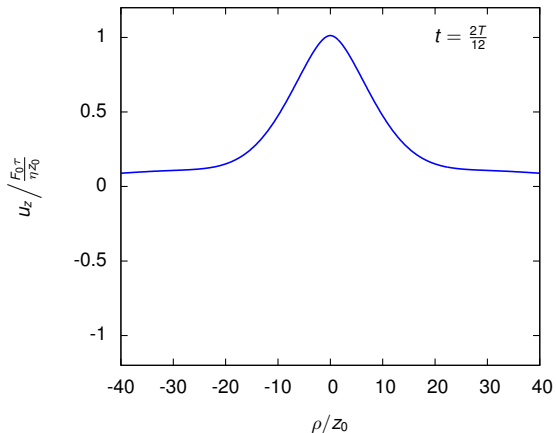
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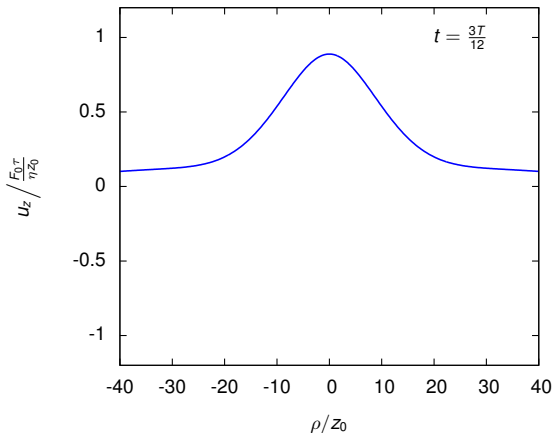
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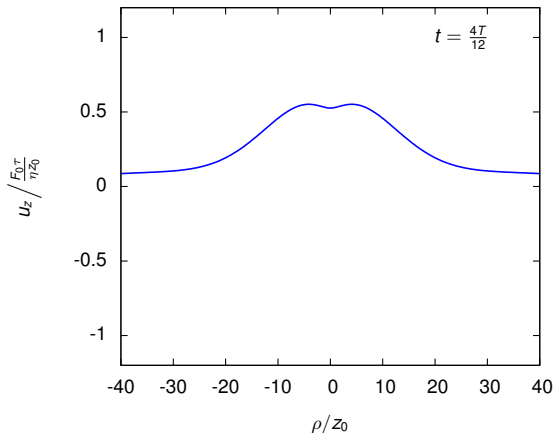
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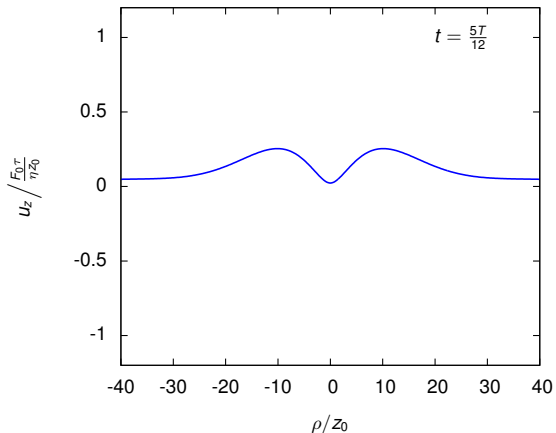
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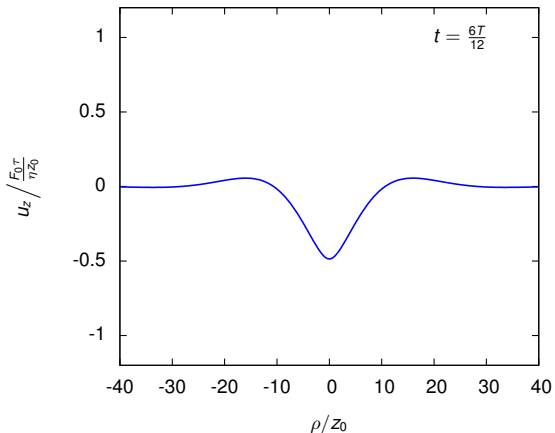
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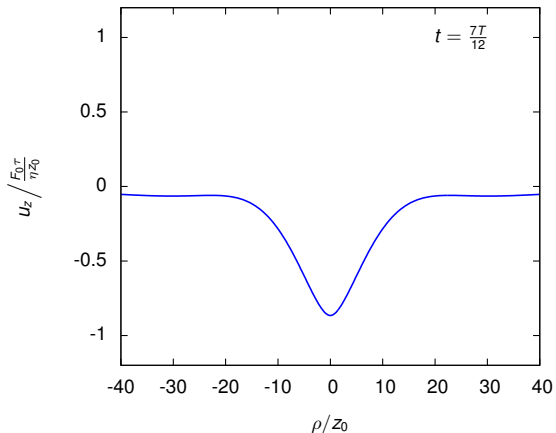
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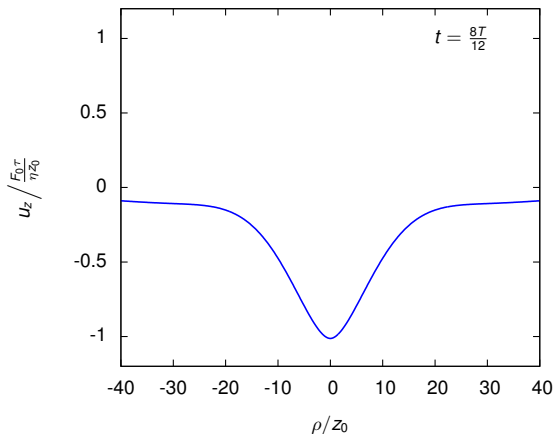
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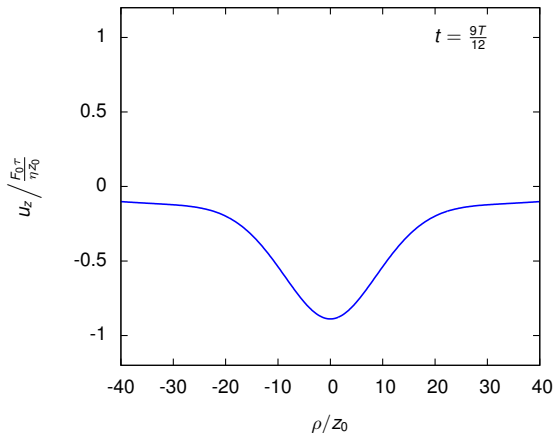
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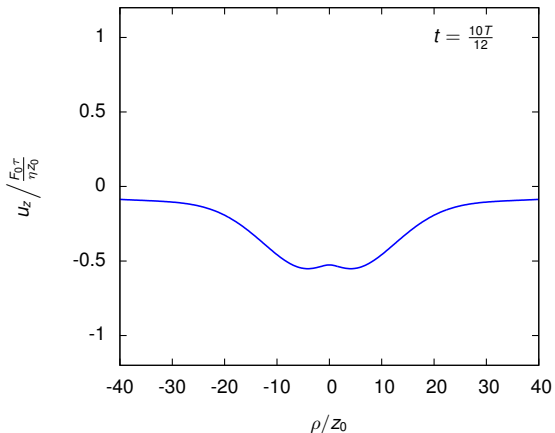
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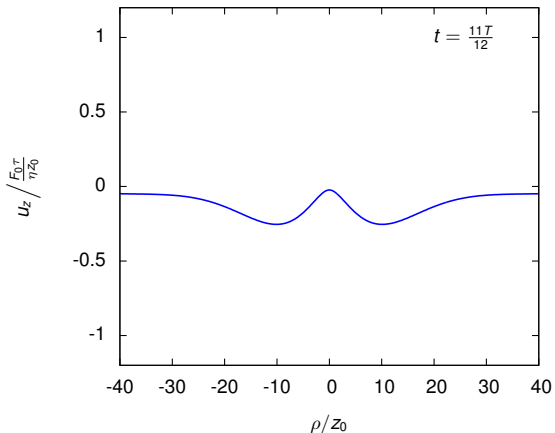
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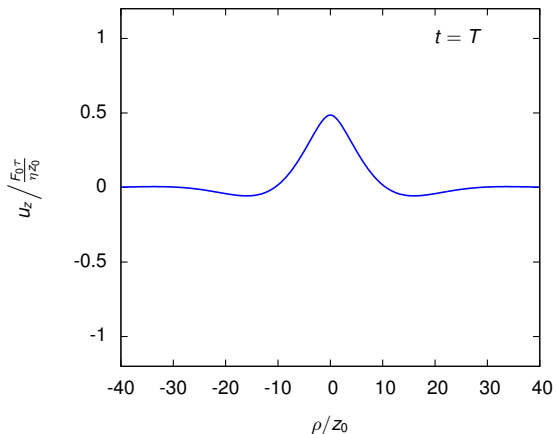
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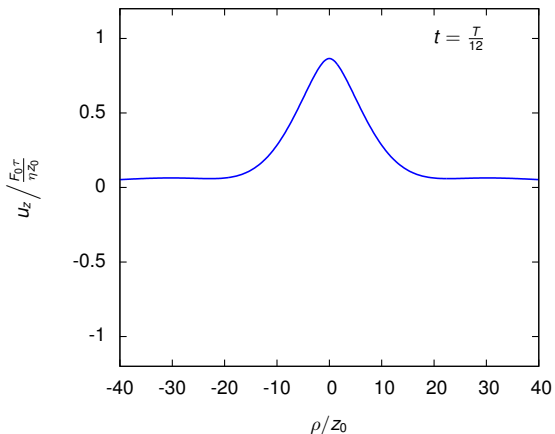
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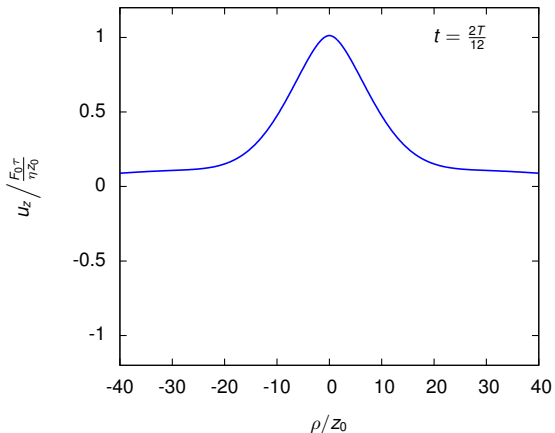
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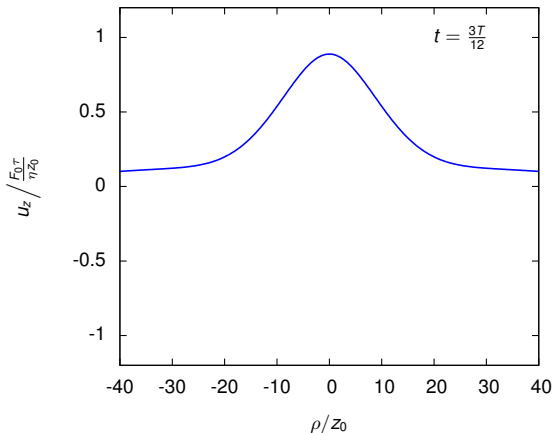
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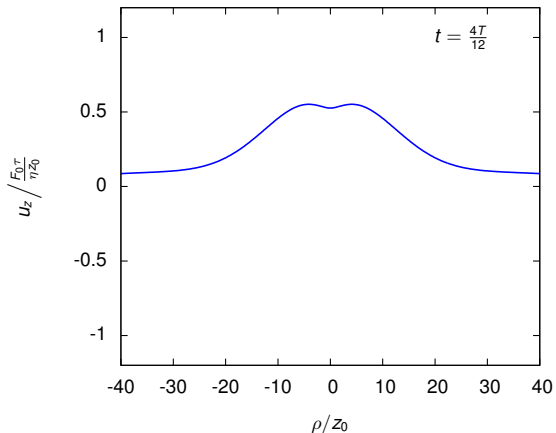
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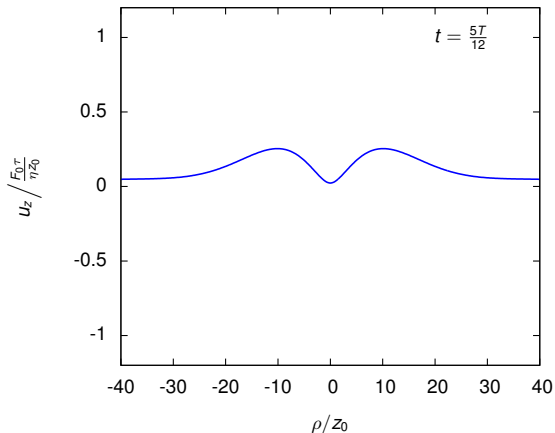
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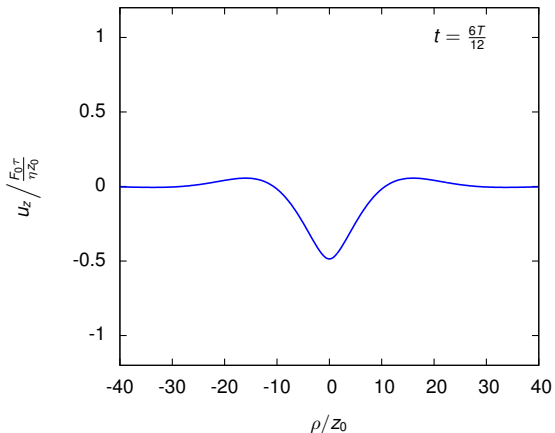
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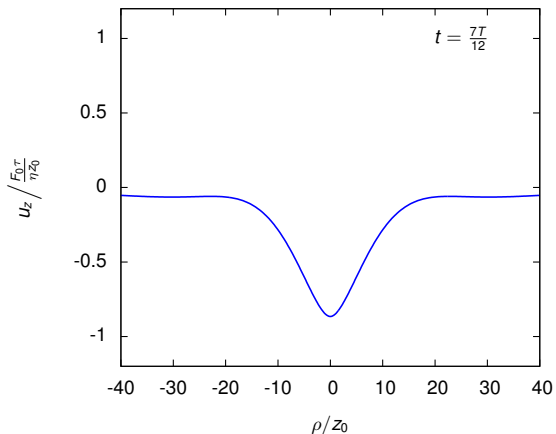
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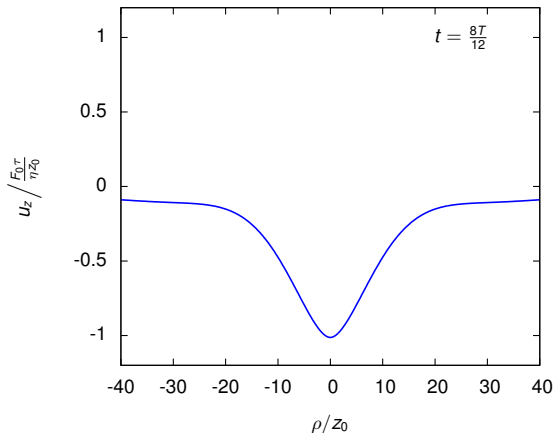
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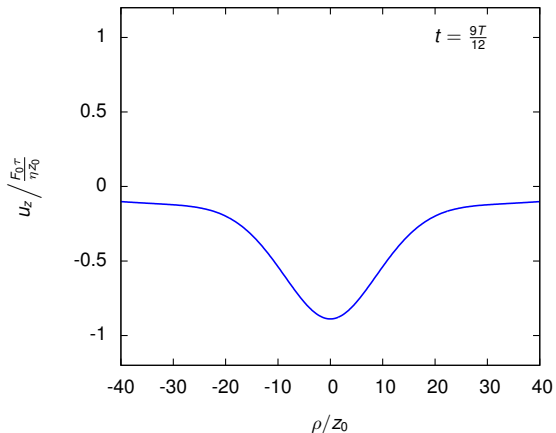
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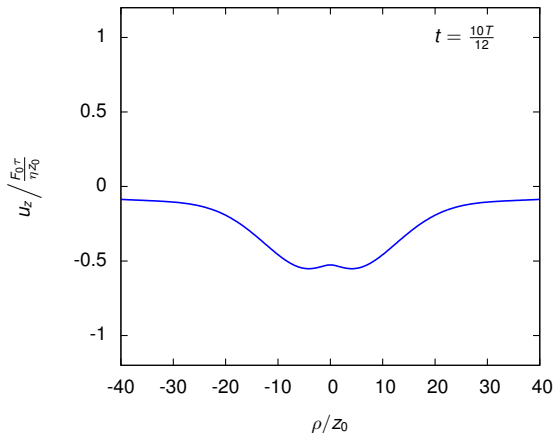
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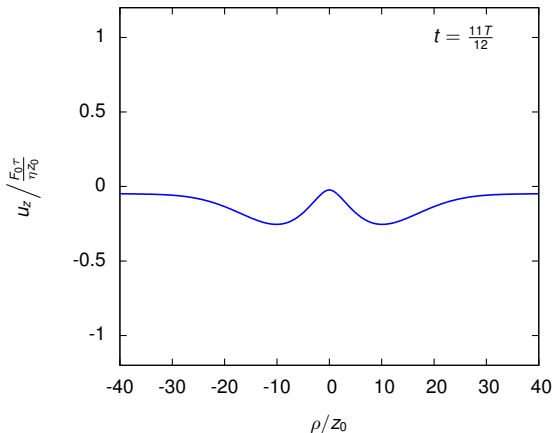
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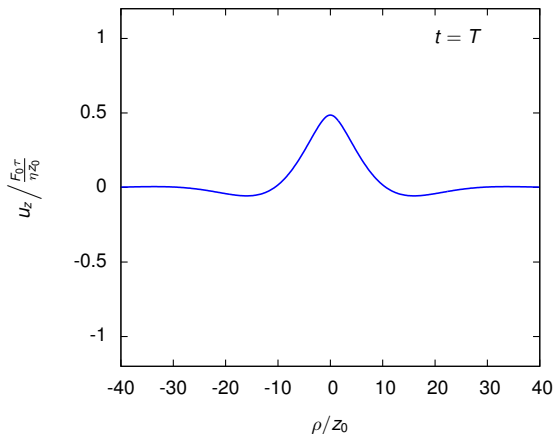
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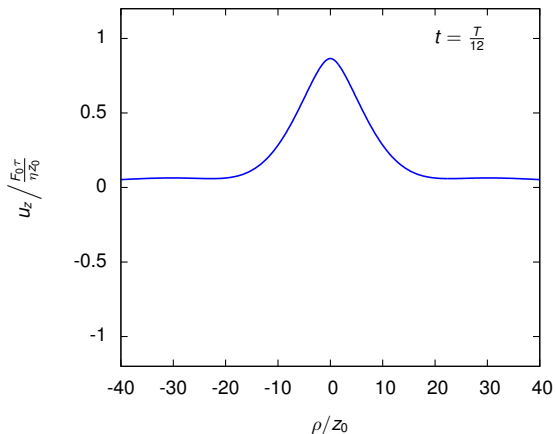
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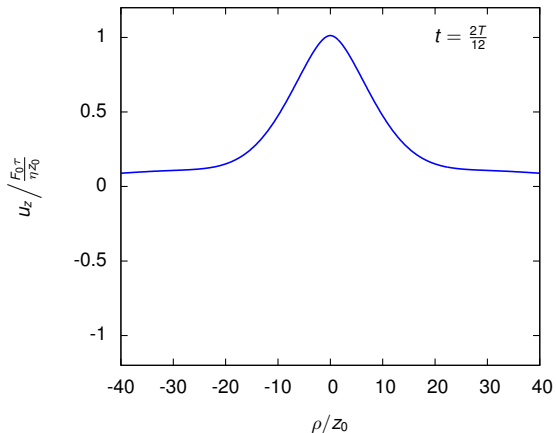
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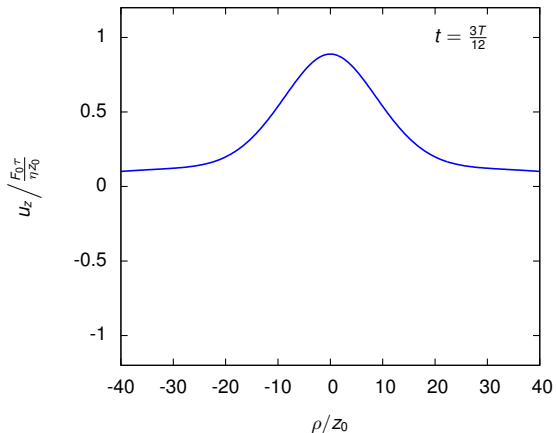
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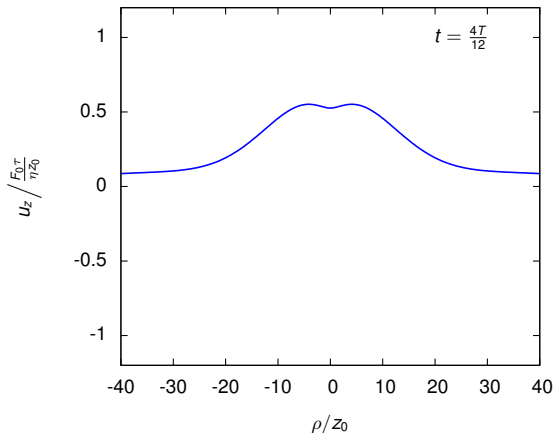
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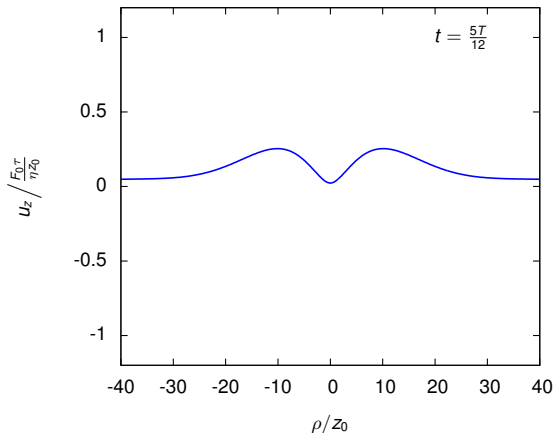
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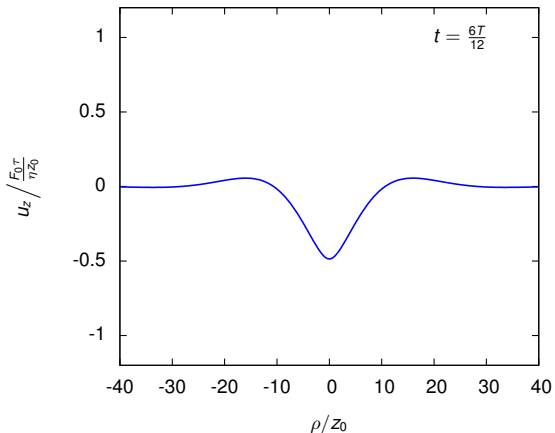
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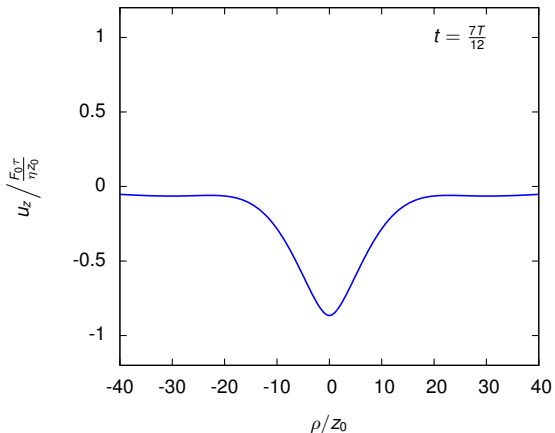
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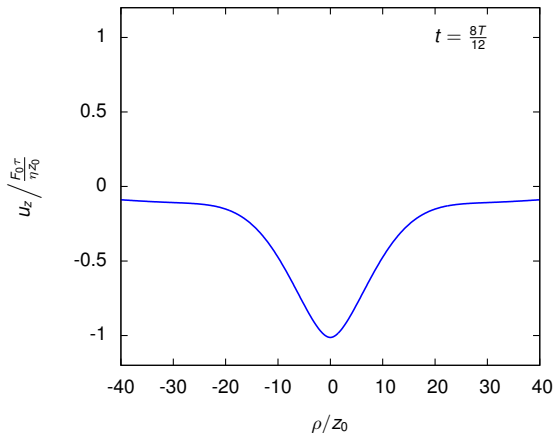
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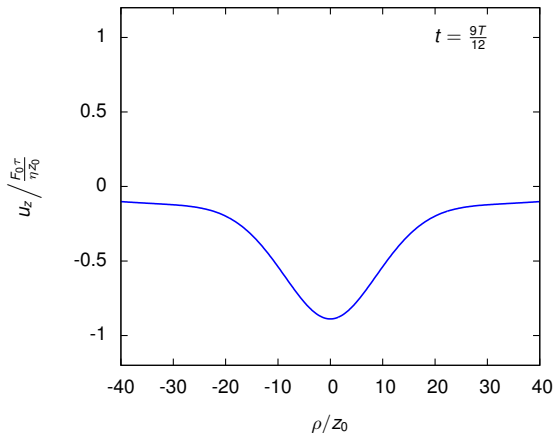
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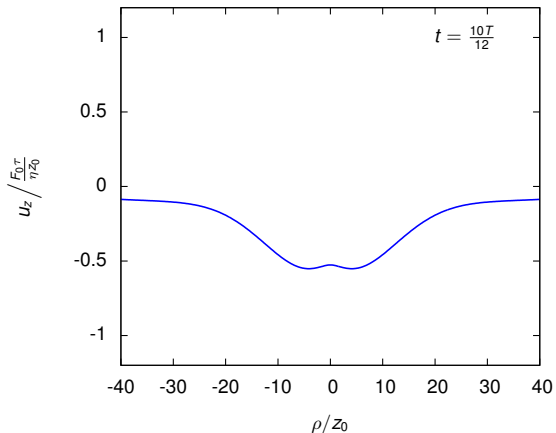
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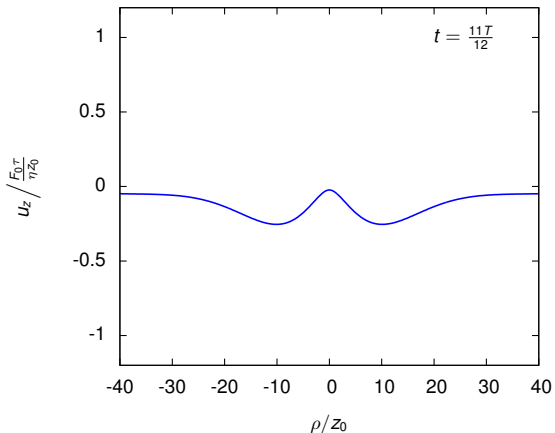
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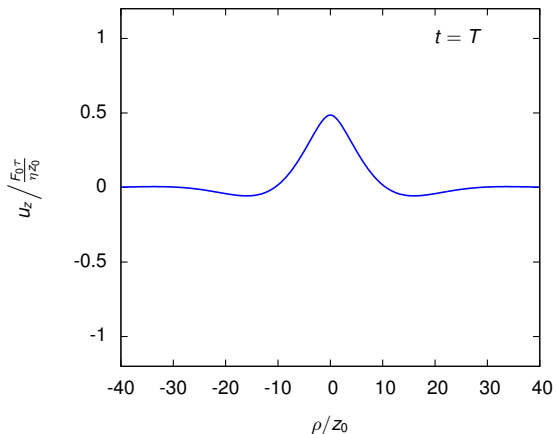
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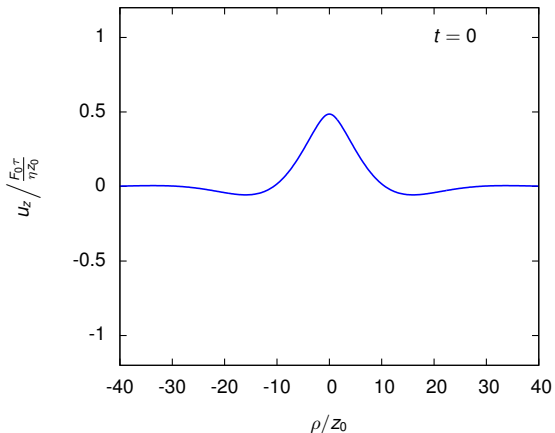
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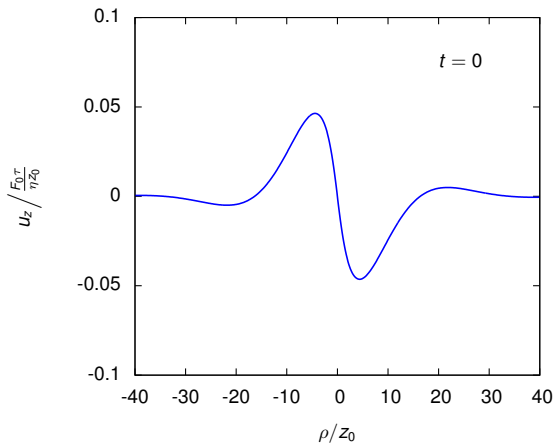


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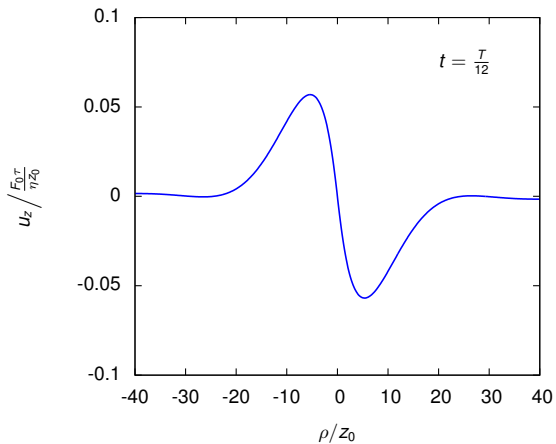
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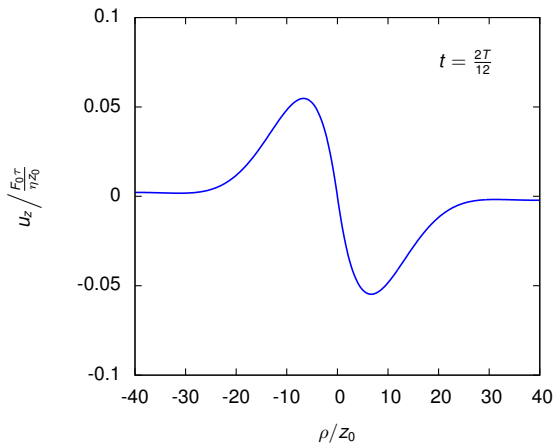
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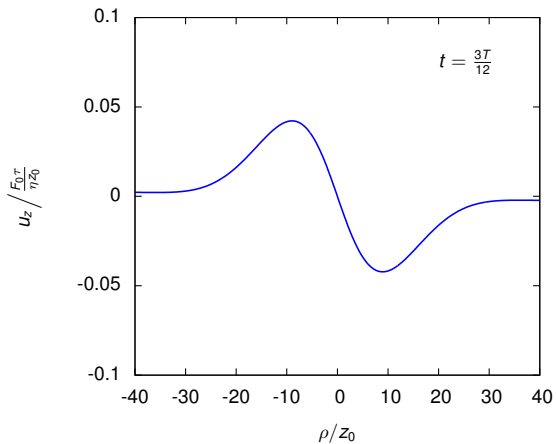
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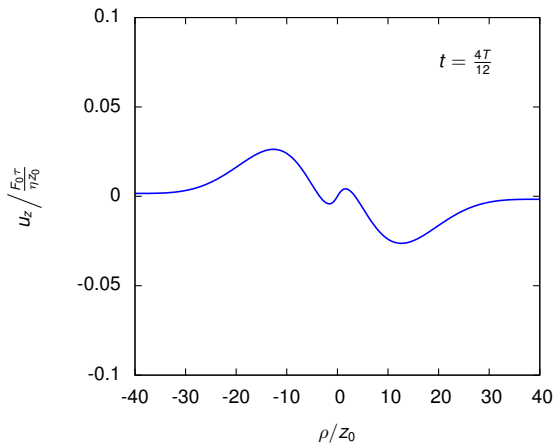
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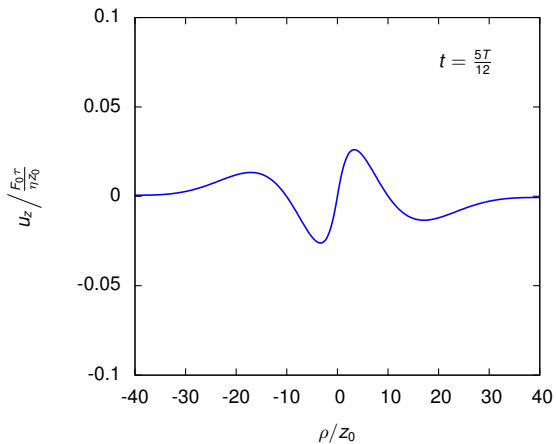
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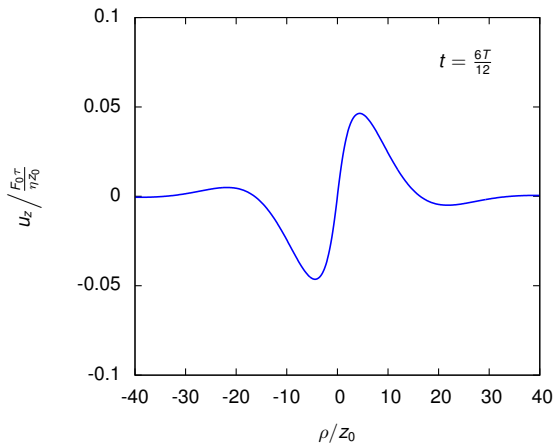
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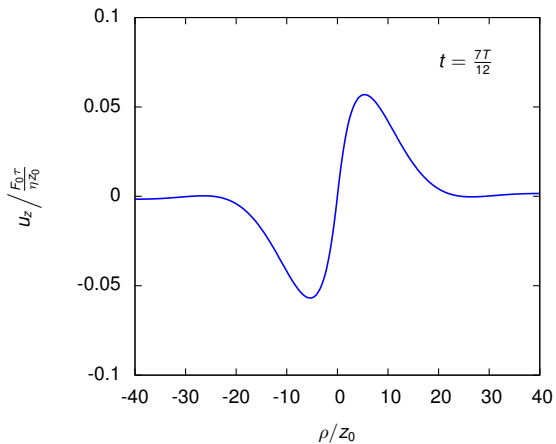
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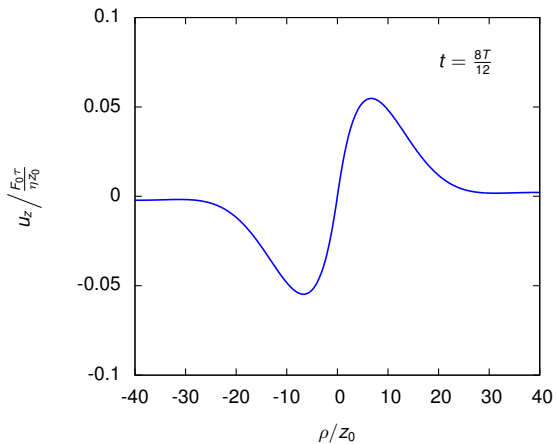
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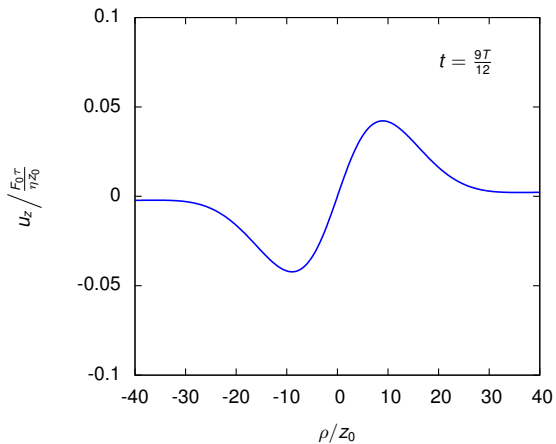
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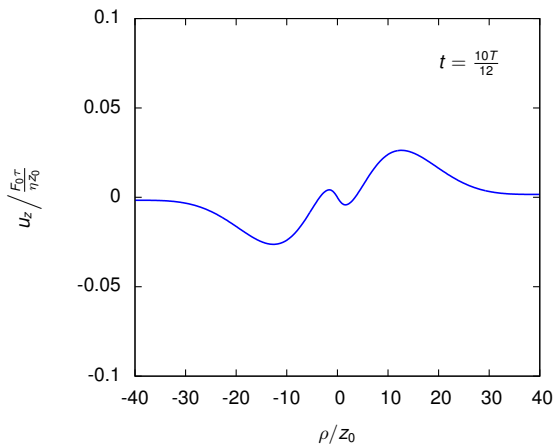
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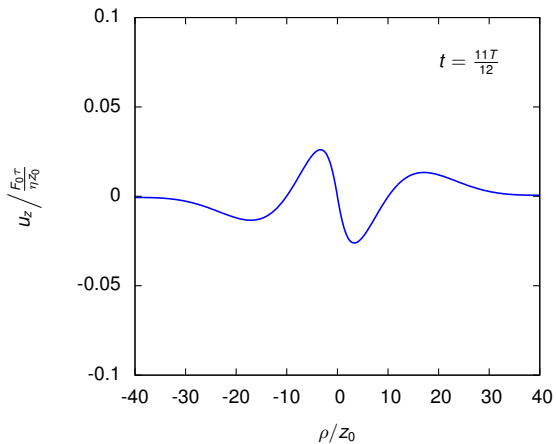
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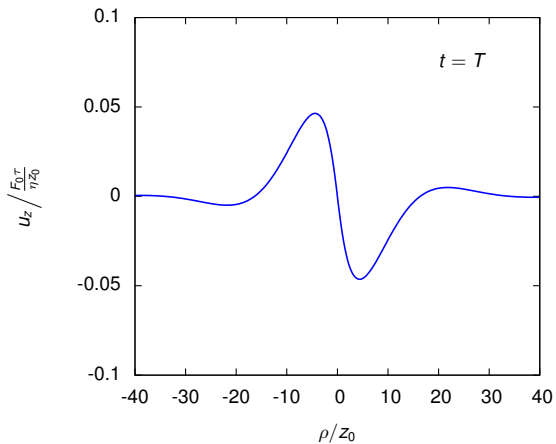
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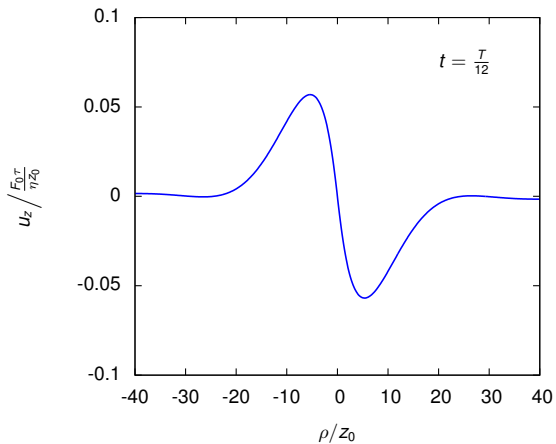
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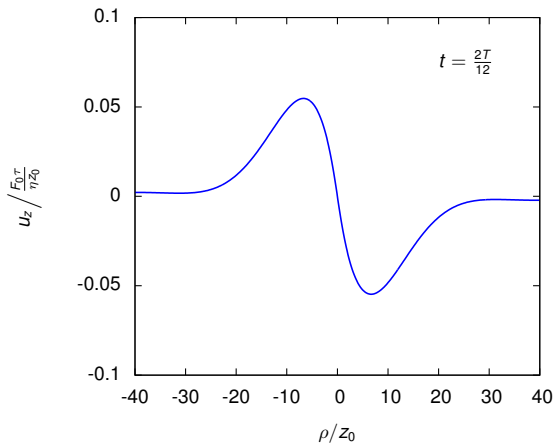
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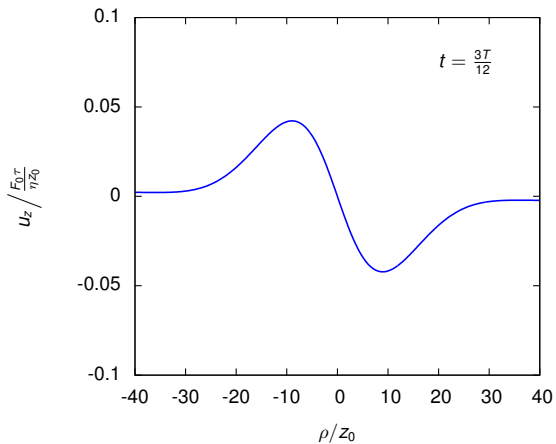
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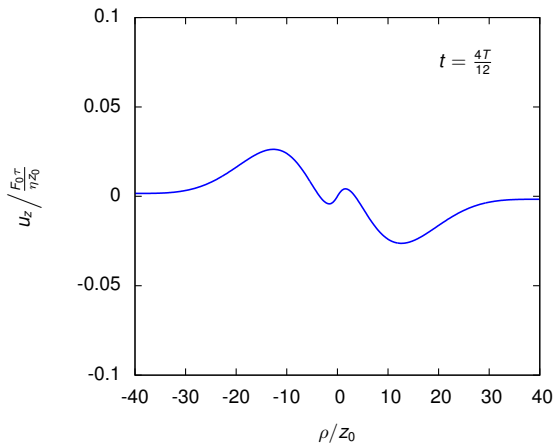
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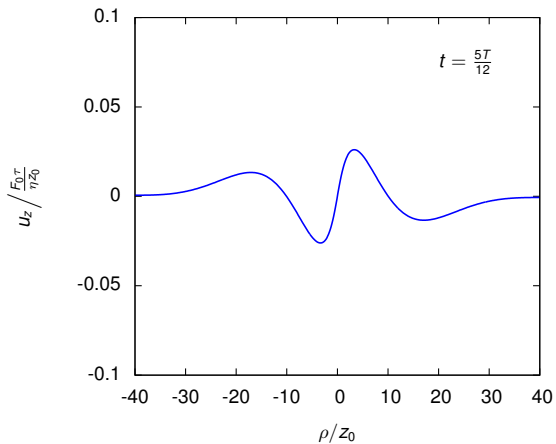
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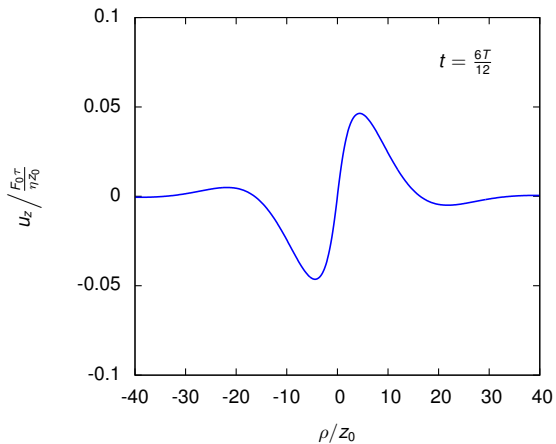
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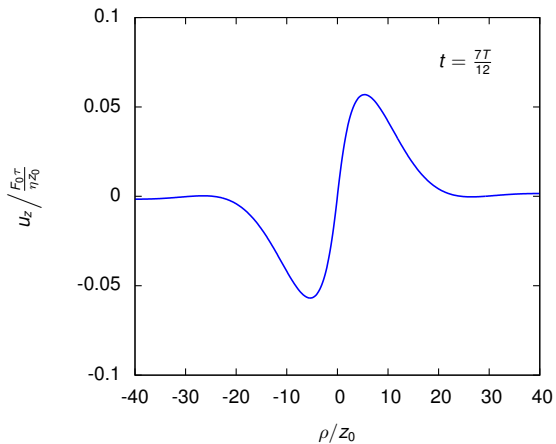
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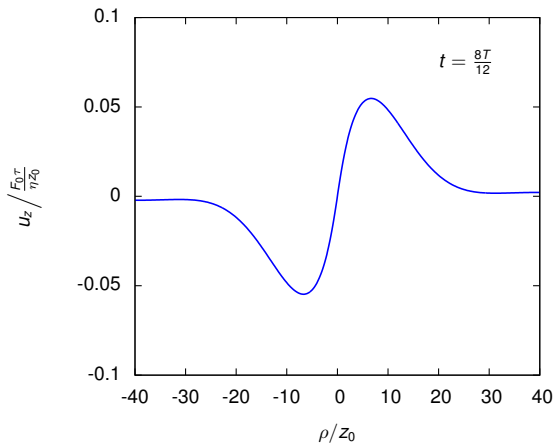
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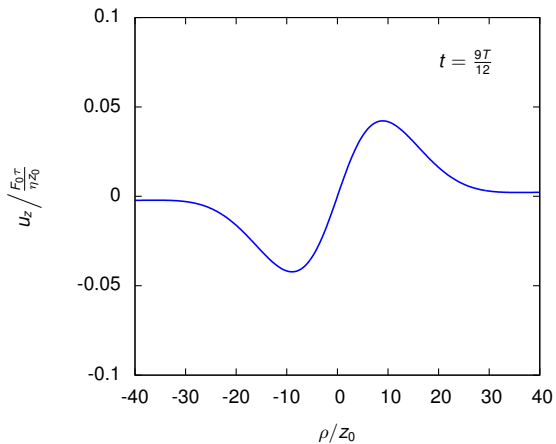
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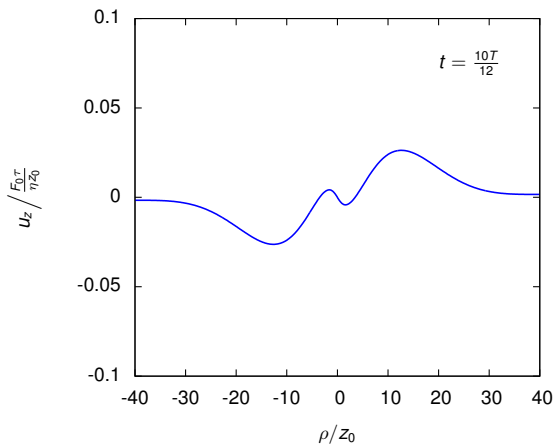
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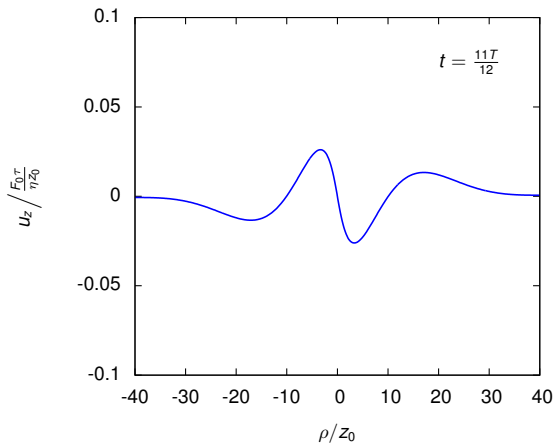
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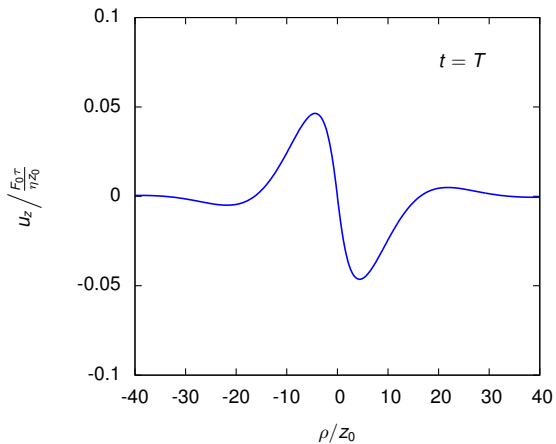
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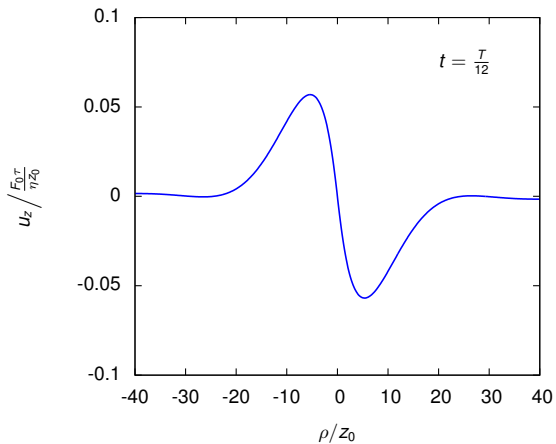
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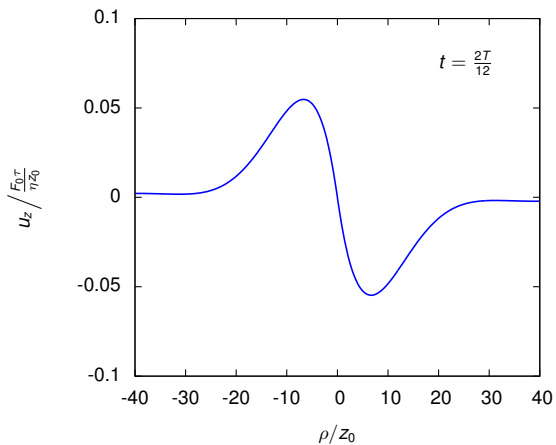
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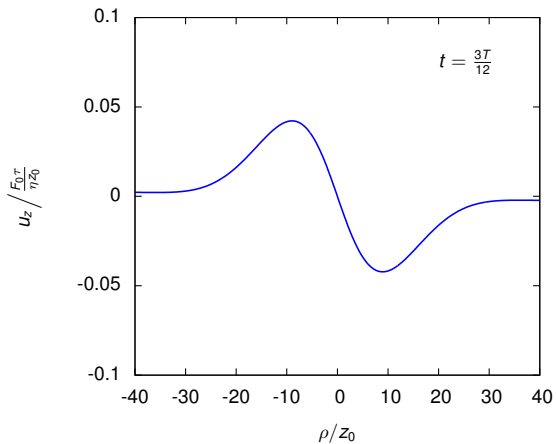
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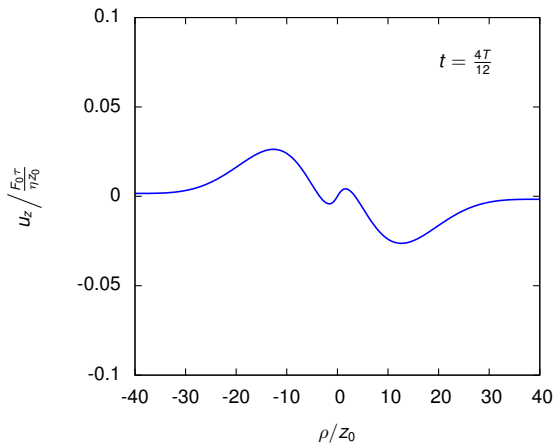
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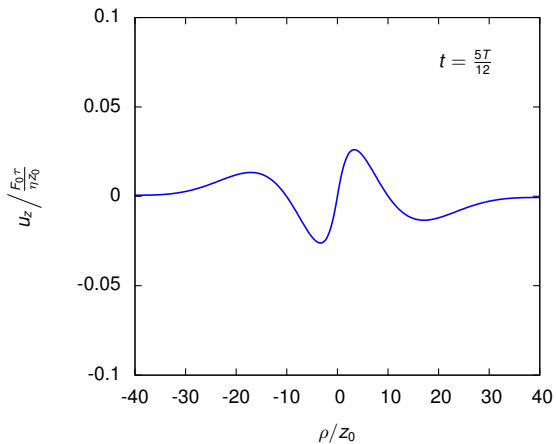
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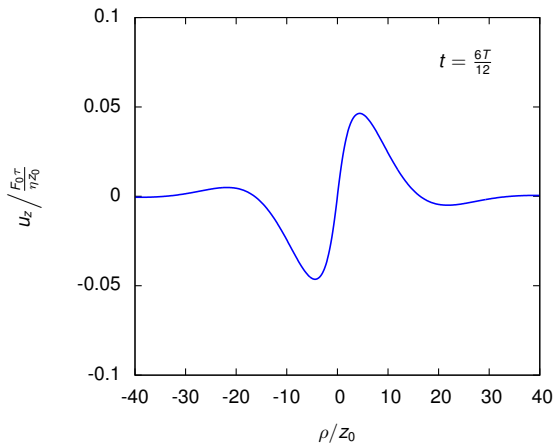
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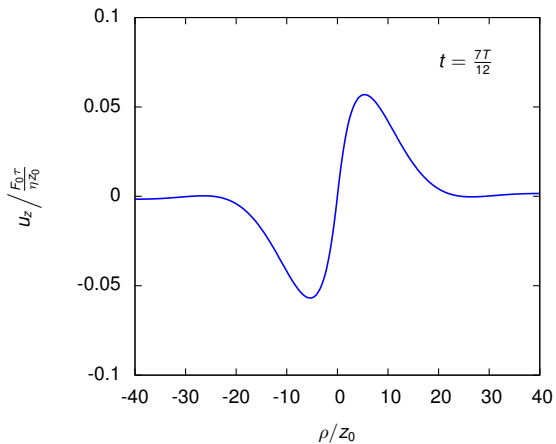
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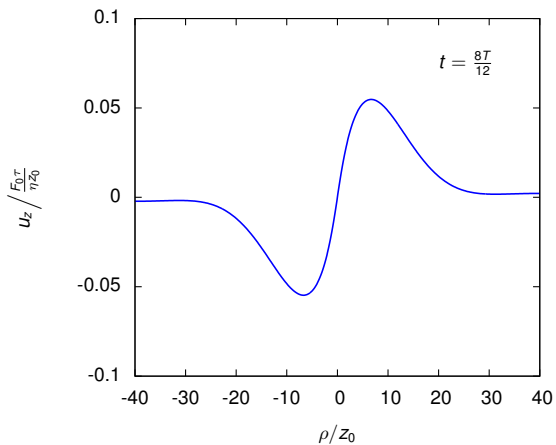
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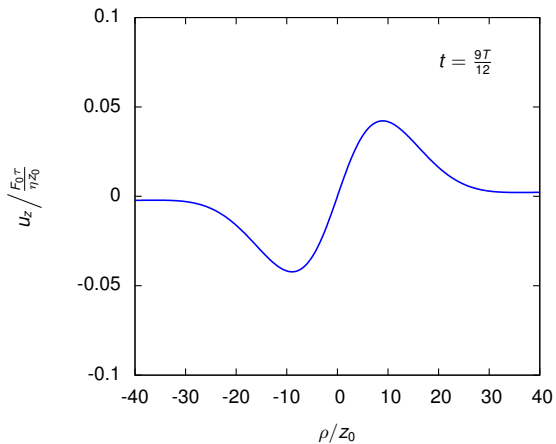
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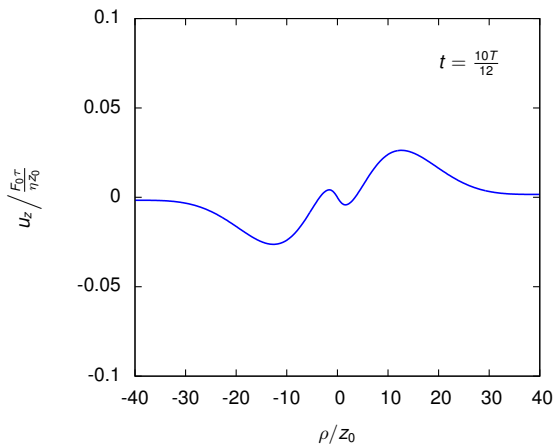
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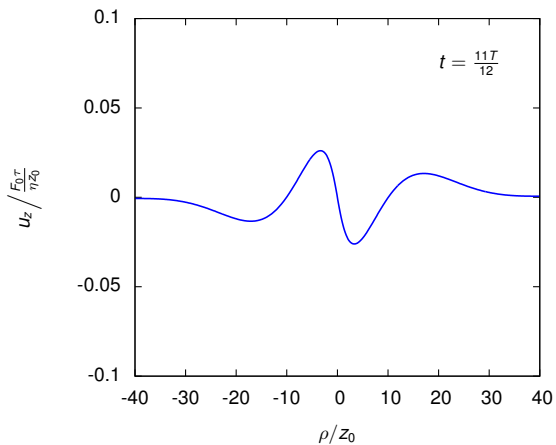
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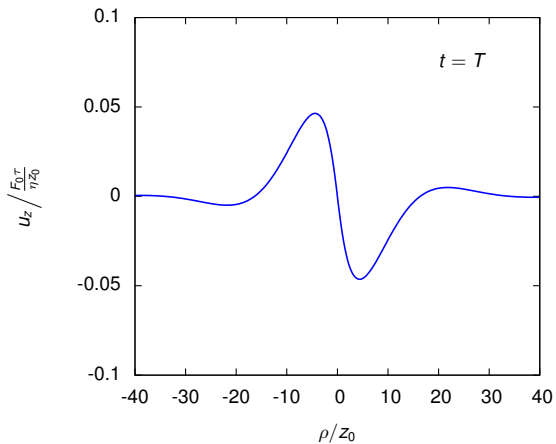
Membrane vertical displacement (Parallel motion)



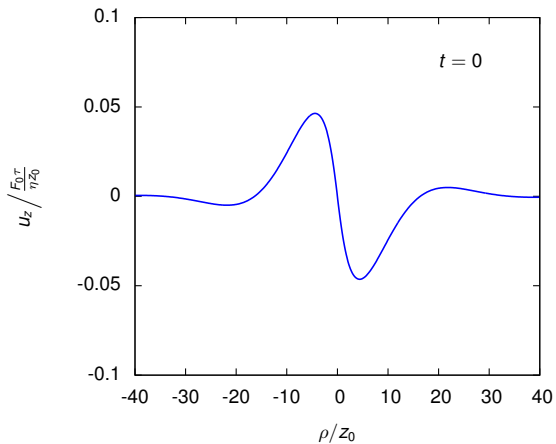
Membrane vertical displacement (Parallel motion)



Membrane vertical displacement (Parallel motion)



Membrane vertical displacement (Parallel motion)



- 1 Introduction
- 2 Mathematical formulation
- 3 Boundary integral simulations
- 4 Results
- 5 Conclusions**

To summarize

- Induced long-lived anomalous diffusion on particles near elastic membranes.
- The long-time diffusion coefficient is identical to that near a hard wall.
- Perpendicular diffusion is significantly slower than parallel diffusion.
- Shear and area dilatation are dominant in the parallel direction whereas bending is dominant in the perpendicular direction.

ADMI, Guckenberger and Gekle Accepted Phys. Rev. E (2016)

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Boundary integral methods

A completed double layer boundary integral equation method is used.

$$v_j(\mathbf{x}) = H_j(\mathbf{x}), \quad \mathbf{x} \in S_m$$

$$\frac{1}{2}\phi_j(\mathbf{x}) + \sum_{i=1}^6 \varphi_j^{(i)}(\mathbf{x}) \langle \varphi^{(i)}, \phi \rangle = H_j(\mathbf{x}), \quad \mathbf{x} \in S_p$$

where

$$H_j(\mathbf{x}) \equiv -\frac{1}{8\pi\eta} (N_m \Delta f_j)(\mathbf{x}) - \frac{1}{8\pi} (K_p \phi)_j(\mathbf{x}) + \frac{1}{8\pi\eta} G_{jk}(\mathbf{x}, \mathbf{x}_c) F_k$$

Zhao, Shaqfeh and Narsimhan, Phys. of Fluids (2012)